## <u>Orthogonal and</u> <u>Orthonormal Vector Sets</u>

We often specify or relate a set of scalar values (e.g., x, y, z) using a set of scalar equations. For example, we might say:

$$x = y$$
 and  $z = x + 2$ 

From which we can conclude a **third** expression:

$$z = y + 2$$

Say that we now add a **new** constraint to the first two:

$$x + y = 2$$

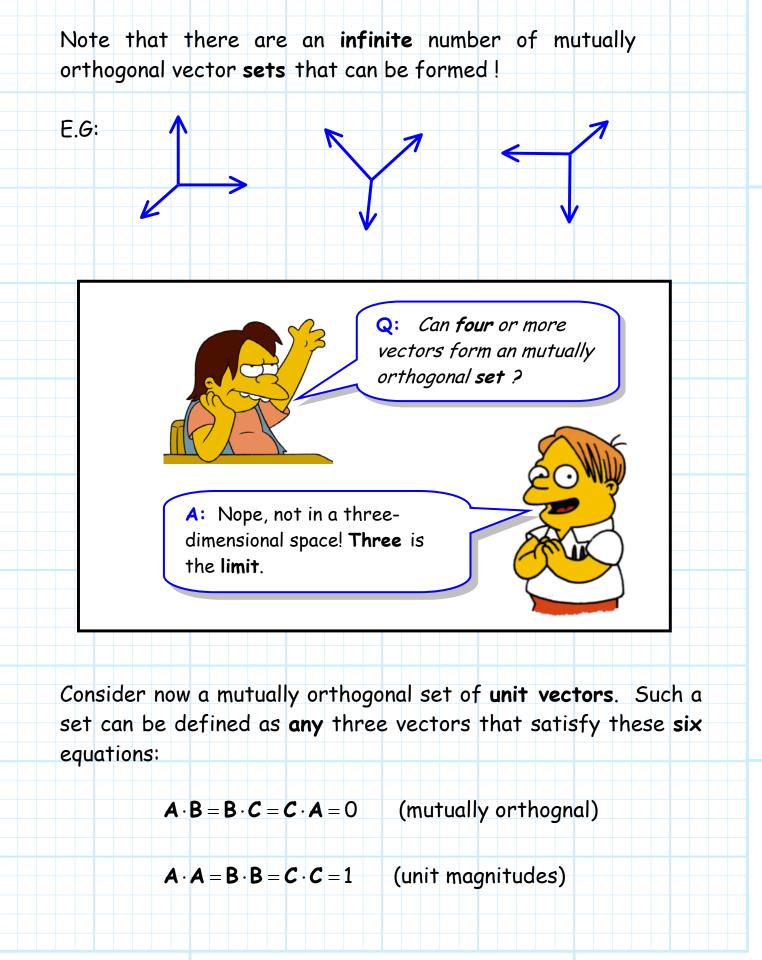
We can now **specifically** conclude that:

$$x=1 \qquad y=1 \qquad z=3$$

Note we can likewise use **vector** equations to specify or relate a set of **vectors** (e.g., **A**, **B**, **C**).

For example, consider a set of **three** vectors that are oriented such that they are **mutually orthogonal** !

In other words, each vector is perpendicular to each of the other two: A В Note that we can describe this orthogonal relationship mathematically using three simple equations:  $\mathbf{A} \cdot \mathbf{B} = 0$  $\mathbf{A} \cdot \mathbf{C} = \mathbf{0}$  $\mathbf{B} \cdot \mathbf{C} = 0$ We can therefore define an orthogonal set of vectors using the dot product: Three (non-zero) vectors A, B and C form an orthogonal set iff they satisfy  $\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{C} = \mathbf{C} \cdot \mathbf{A} = 0$ Jim Stiles The Univ. of Kansas Dept. of EECS



$$\hat{a}_{A}\cdot\hat{a}_{B}=\hat{a}_{B}\cdot\hat{a}_{C}=\hat{a}_{C}\cdot\hat{a}_{A}=0$$

Again, there are an **infinite** number of **orthonormal** vector sets, but each set consists of only **three** vectors.